

A Study on "Path" function in LALR Parsing Method

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〈Abstract〉

The set-valued function "Path" is presented recently as a new tool for the analysis of LALR parsing method.

In this paper, a new algorithm using Digraph is introduced for efficient computation of Path. Several characteristics of path is also studied with a new relation and an associated graph.

LALR Parsing 방법에서의 "Path" function에 관한 연구

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〈요 약〉

"Path" function은 LALR formalism에 대한 새로운 해석을 위한 도구로서 정의된 함수이다. 본 논문에서는 이 함수의 계산을 위하여 Digraph algorithm을 이용한 효율적인 계산방법이 고안되었으며, 이 함수의 여러가지 특성이 새로운 relation과 관계된 graph를 통하여 연구되었다.

I. Introduction

The set-valued function "Path" is presented recently as a new tool for the analysis of LALR parsing method[1]. The main result of this new analysis can be stated by the following formula.

$$\begin{aligned} & \text{LA}_s(P, [A \rightarrow \alpha_1 \alpha_2]) \\ &= \{x | x \in \text{Path}_s(A', A) \oplus_s \text{FIRST}_s(\beta_2) \\ & \quad \oplus_s \text{LA}_s(q, [B \rightarrow \beta_1 A' \beta_2]), \\ & \quad q \in \text{PRED}(q, \alpha_1), A_1 L^* A, \\ & \quad [B \rightarrow \beta_1 A' \beta_2] \in K_s\}. \end{aligned}$$

Hence an efficient computation of Path_1 is necessary to compute LALR(1) lookahead sets efficiently.

Moreover Path has its own interesting characteristics.

But these are not been fully studied. In this paper, Path is studied deeply. In addition, a new computation algorithm for Path_1 is introduced by some new relations and Digraph algorithm[4].

II. Basic terminology and definitions

The basic terminology and definitions in this paper are consistent with those of Aho and Ullman [2,3]. Notational conventions are also stated.

A context-free grammar(CFG) is a quadruple (N, T, P, S) , where N, T, P , and S stand, respectively, for a set of nonterminal symbols,

a set of terminal symbols, a set of productions (each of which is of the form $A \rightarrow \alpha$), and a start symbol in N . Given a grammar G, V (the vocabulary) stands for $N \cup T$ and V^* for the reflexive-transitive closure of V ; the transitive closure is indicated by the superscript⁺.

Lower-case Greek letters such as α, β, γ , and ω denote strings in V^* , lowercase Roman letters toward the beginning of the alphabet (a, b , and c) are terminals, whereas those near the end (u, v , and w) are strings in T^* ; upper-case letters in the beginning of the alphabet (A, B , and C) are nonterminals, whereas those near the end (X, Y , and Z) are symbols in V . An empty string is denoted by Λ . Given a relation R , R^* stands for the reflexive-transitive closure of R ; and R^+ for the transitive closure of R and R^{-1} for the inverse relation of R ; and following notations are used; $R(A) = \{B \mid ARB\}$ and $R^{-1}(A) = \{B \mid BRA\}$.

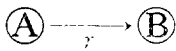
We take for granted concepts such as FIRST_k and \oplus_k . And RHS (or LHS) stands for the right-hand (or left-hand) side of a production or a formula.

The following concepts are introduced by [1].

[Definition 2.1] We define a left dependency relation

$$L \subseteq N \times N : A L B \text{ iff } A \rightarrow B\gamma \in P. \quad (2.1)$$

We also call the directed graph associated with relation L the L -graph. It is constructed by representing each instance of (2.1) as a pair of vertices connected by a directed edge:

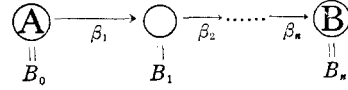


Note that the edge has been labeled with the remaining part of the production RHS that follows B . The following definition is also from [1].

[Definition 2.2] For any nonterminals A and B ,

$$\begin{aligned} \text{Path}_k(A, B) &= \{ \text{FIRST}_k(\beta_n \cdots \beta_2 \beta_1) \mid B_0 = A, \\ &\quad B_n = B, \ n \geq 0, \ B_0 \rightarrow B_1 \beta_1 \in P, \\ &\quad B_1 \rightarrow B_2 \beta_2 \in P, \dots, \\ &\quad B_{n-1} \rightarrow B_n \beta_n \in P \}, \end{aligned} \quad (2.2)$$

where the sequence β_1, \dots, β_n describes a path from A to B in the L -graph of the form



In this formula, the \cup stands for union overall such paths from A to B .

Now we redefine this concept for clarifying further discussion.

[Definition 2.3]

For any nonterminals A and B ,

$$\text{Path}_k^1(A, B) = \{ \text{FIRST}_k(u) \mid A \rightarrow Bu \in P \} \quad (2.3)$$

$$\begin{aligned} \text{Path}_k^*(A, B) &= \cup (\text{Path}_k^1(C_i, B) \oplus_k \text{Path}_k^{*-1} \\ &\quad (A, C_i)) C_i \in \{C \mid A L^{*-1} C, CLB\} \end{aligned} \quad (2.4)$$

for $n \geq 2$.

$$\text{Path}_k(A, B) = \bigcup_{i=1}^{\infty} \text{Path}_k^i(A, B) \quad (2.5)$$

Observe that a simple consideration give us the fact that formula (2.2) and formula (2.5) are equivalent. The formula (2.2) can be restated by

$$\begin{aligned} \text{Path}_k(A, B) &= \cup \{ \beta_n \oplus_k \beta_{n-1} \oplus_k \cdots \oplus_k \beta_2 \oplus_k \beta_1 \mid B_0 \\ &= A, \ B_n = B, \ n \geq 1, \\ &\beta_i \in \text{Path}_k^1(B_{i-1}, B_i) \text{ for} \\ &\quad 1 \leq i \leq n \} \end{aligned} \quad (2.6)$$

with the same descriptions in (2.2).

Now we define a new useful relation η .

[Definition 2.4]

$$A \eta B \text{ iff } \Lambda \in \text{Path}_k^1(A, B) \text{ for } k \geq 1. \quad (2.7)$$

In addition, notice that the followings are obviously true.

$$A L B \text{ iff } \text{Path}_k^1(A, B) \neq \emptyset \quad (2.8)$$

$$A L B \text{ if } A \eta B. \quad (2.9)$$

$$A \eta^+ B \text{ iff } \Lambda \in \text{Path}_k(A, B). \quad (2.10)$$

$$A L^+ B \text{ iff } \text{Path}_k(A, B) \neq \emptyset. \quad (2.11)$$

III. Computing Path_k by a direct method.

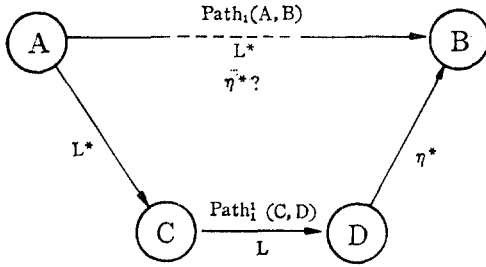
In this section, a useful theorem for comp-

uting Path directly is introduced, and also derived algorithm is stated.

[Theorem 3.1]

$$\text{Path}_1(A, B) = \bigcup_{\substack{C \in L^*(A) \\ D \in \eta^{+*}(B) \\ C L D}} (\text{Path}_1^i(C, D) - \{A\}) \cup \{A \mid A \eta^+ B\} \quad (3.1)$$

Proof. First, we will prove $\text{LHS}(3.1) \subseteq \text{RHS}(3.1)$. Assume $A \in \text{Path}_1(A, B)$. Then $A \eta^+ B$ by formula (2.10). Hence $A \in \text{RHS}(3.1)$. Assume $a \in \text{Path}_1(A, B)$. Then by formula (2.6), a must be some β_i , i.e., $a \in \text{Path}_1^i(B_{i-1}, B_i)$. Then the fact that $A L^* B_{i-1}$ and $B_{i-1} L B_i$ is simply true by the concept of L^* and (2.8). Further, since $A \in \text{Path}_1(B_i, B)$ or $B_i = B$ by the property of \oplus_1 operator, $B_i \eta^* B$ is true by (2.10). Hence $a \in \text{RHS}(3.1)$



⟨Fig. 3.1⟩

Next let us prove $\text{LHS}(3.1) \supseteq \text{RHS}(3.1)$. If $A \in \text{RHS}(3.1)$, then $A \eta^+ B$.

Hence $A \in \text{Path}_1(A, B)$. Assume $a \in \text{RHS}(3.1)$. Then a must be contained some direct path, say, $\text{Path}_1^i(B_{i-1}, B_i)$ with nonterminals B_{i-1} and B_i satisfying appropriate conditions. Then figure (3.1) simply shows that $\text{Path}_1^i(B_{i-1}, B_i) \subseteq \text{Path}_1(A, B)$ by the property of η^* and formula (2.6).

Hence $a \in \text{Path}_1(A, B)$. This completes the proof. The following formula is equivalent to formula (3.1) and more useful for computing Path.

$$\text{Path}(A, B) = \bigcup_{\substack{C \in L^*(A) \\ D \in \eta^{+*}(B) \\ C L D}} (\text{Path}_1^i(C, D) \cup \{A \mid A \eta^+ B\}) - \{A \mid \text{not}(A \eta^+ B)\} \quad (3.2)$$

This formula yields the following algorithm

for computing Path.

⟨Algorithm 3.1⟩

```

Compute  $L^+$ 
Compute  $\eta^+$ 
/* initially  $\text{path}_1(A, B) := \phi$  */
for  $A \in N$  do
  for  $B \in N$  do
    if  $A L^+ B$  then
      for  $C \in L^*(A)$  do
        for  $D \in \eta^{+*}(B)$  do
          if  $C L D$  then
             $\text{Path}_1(A, B) := \text{Path}_1(A, B) \cup \text{Path}_1^i(C, D)$ 
          endif
        endfor
      endfor
    if  $(A \eta^+ B)$  then  $\text{Path}_1(A, B)$ 
      :=  $\text{Path}_1(A, B) \cup \{A\}$ 
    else  $\text{Path}_1(A, B) := \text{Path}_1(A, B) - \{A\}$ 
    endif
  endif
endfor
endfor

```

V. Computing Path by Traversing a Digraph

Algorithm 3.1 correctly computes Path, but the same thing is computed more than once in finding all Path. This inefficiency can be eliminated by the following formalisms and the derived computing algorithm.

[Lemma 4.1]

If $A L^+ B$, $A L C$, and $C L^+ B$,

Then $\text{Path}_1(A, B) \supseteq \text{Path}_1(C, B) - \{A\}$

This Lemma is trivial from following figure and formula (2.6).

But it should be noted that when $\text{Path}_1(C, B)$ contains A , $\text{Path}_1(A, B)$ include $\text{Path}_1(C, B)$ except A . $\text{Path}_1(A, B)$ can contain A if and only if $A \eta^+ B$.

end Digraph

In virtue of [Theorem 4.1] and [Theorem 4.2], we can compute $\overline{\text{Path}}_1$ in a efficient way.

Now, we can get the final result by the following formula.

$$\text{Path}_1(A, B) = \overline{\text{Path}_1(A, B)} - \{A \mid \text{not } (A \eta^+ B)\}.$$

V. Conclusion

Several characteristics of Path are studied, and formalisms for computing Path are developed.

In virtue of these formalisms, the meaning of Path is clarified and an efficient computation method is derived. This method uses Digraph algorithm associated with relation " I " which nicely captures inclusions in Path sets. The application of this method to LALR(1) parser generating system can reduce the computation time for LALR(1) lookahead sets.

References

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